

INSPECTION OF CONFINED STRUCTURES

CT2MC offers, through its CAN'EAU® range, autonomous inspection solutions for confined structures, particularly focusing on wastewater networks.

Our CAN'EAU® Range:

- Facilitates Asset Inspection: The CAN'EAU® drones are equipped with advanced technologies, including 360° cameras, allowing for continuous video capture of pipelines from all angles. This enables operators to conduct thorough assessments of infrastructure conditions.
- Highly Adaptable: The range includes both floating and rolling drones, designed to navigate various confined environments such as potable water pipelines and wastewater networks with diameters exceeding 400 mm.
- Reduces Human Risks: By deploying autonomous drones, CT2MC minimizes the need for human entry into hazardous or hard-to-reach areas, thereby enhancing safety during inspections.

CEM001 CLD001 CSR001 RTO001









Ø 400 mm 30 mm 115 mm 4h

Ø 500 mm 90 mm 150 mm 6h

MINIMUM PIPE DIAMETER: 800 mm DRAFT: 150 mm AIR DRAFT: 230 mm AUTONOMY: up to 4 hours

Ø 400 mm

4h

OUR TECHNOLOGIES

INSPECTION CCTV footage and inspect the structure as if they were physically inside it.	STRUCTURE	Equipped with a 360° camera, the system captures the entire structure (above the
Multiple lamps provide diffuse 360° illumination with calibrated color and adjustable intensity, tailored to the size of the structure. POSITIONING By deploying positioning beacons along the inspection route, the exact location of the inspection tool within the structure is accurately determined. SEDIMENTATION PROFILING DETECTION OF INFILTRATION OF CLEAN WATER (ECCPP) The system can detect the presence of gases such as hydrogen sulfide (H₂S), carbon monoxide (CO), oxygen (O₂), and methane (CH₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPELINE TRAJECTORY Multiple lamps provide diffuse of the structure. By deploying positioning beacons along the inspection route, the exact location of the inspection of a sediment profile throughout the exact location of the entire structure. A rotating sonar enables the creation of a sediment profile throughout the entire structure. Integrated water quality sensors (measuring conductivity, temperature, and/or pH) detect anomalies in key parameters, indicating the presence of unwanted clean water infiltration. CEAN WATER (ECPP) The system can detect the presence of gases such as hydrogen sulfide (H₂S), carbon monoxide (CO), oxygen (O₂), and methane (CH₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point	INSPECTION	waterline) in a single pass. During post-processing, operators can navigate through the
intensity, tailored to the size of the structure. POSITIONING By deploying positioning beacons along the inspection route, the exact location of the inspection tool within the structure is accurately determined. SEDIMENTATION PROFILING DETECTION OF INFILTRATION OF CLEAN WATER (ECPP) The system can detect the presence of gases such as hydrogen sulfide (H ₂ S), carbon monoxide (CO), oxygen (O ₂), and methane (CH ₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPPLINE TRAJECTORY Internation to the exact location of the inspection route, the exact location of the entire structure. A rotating position the extructure and/or pH) detect anomalies in key parameters, indicating the presence of unwanted clean water infiltration. The system can detect the presence of gases such as hydrogen sulfide (H ₂ S), carbon monoxide (CO), oxygen (O ₂), and methane (CH ₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPPLINE TRAJECTORY The embedded technologies produce a file containing X, Y, and Z coordinates. When co	(CCTV)	footage and inspect the structure as if they were physically inside it.
inspection tool within the structure is accurately determined. SEDIMENTATION PROFILING DETECTION OF INFILTRATION OF CLEAN WATER (ECPP) The system can detect the presence of gases such as hydrogen sulfide (H ₂ S), carbon monoxide (CO), oxygen (O ₂), and methane (CH ₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPELINE TRAJECTORY The arbota water quality sensors (measuring conductivity, temperature, and/or pH) detect anomalies in key parameters, indicating the presence of unwanted clean water infiltration. A rotating sonar enables the creation of a sediment profile throughout the entire structure. And/or pH) detect anomalies in key parameters, indicating the presence of unwanted clean water infiltration. The system can detect the presence of gases such as hydrogen sulfide (H ₂ S), carbon monoxide (CO), oxygen (O ₂), and methane (CH ₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPELINE The embedded technologies produce a file containing X, Y, and Z coordinates. When combined with surface georefe	LIGHTING	·
DETECTION OF Integrated water quality sensors (measuring conductivity, temperature, and/or pH) detect anomalies in key parameters, indicating the presence of unwanted clean water infiltration. The system can detect the presence of gases such as hydrogen sulfide (H ₂ S), carbon monoxide (CO), oxygen (O ₂), and methane (CH ₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPELINE TRAJECTORY The embedded technologies produce a file containing X, Y, and Z coordinates. When combined with surface georeferencing information, this allows for precise mapping of the structure's position. Depending on the conditions, the system utilizes either four aerial turbines or two	POSITIONING	
INFILTRATION OF CLEAN WATER (ECPP) The system can detect the presence of gases such as hydrogen sulfide (H ₂ S), carbon monoxide (CO), oxygen (O ₂), and methane (CH ₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPELINE TRAJECTORY The embedded technologies produce a file containing X, Y, and Z coordinates. When combined with surface georeferencing information, this allows for precise mapping of the structure's position. Depending on the conditions, the system utilizes either four aerial turbines or two		A rotating sonar enables the creation of a sediment profile throughout the entire structure.
The system can detect the presence of gases such as hydrogen sulfide (H ₂ S), carbon monoxide (CO), oxygen (O ₂), and methane (CH ₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPELINE TRAJECTORY The embedded technologies produce a file containing X, Y, and Z coordinates. When combined with surface georeferencing information, this allows for precise mapping of the structure's position. Depending on the conditions, the system utilizes either four aerial turbines or two	DETECTION OF	Integrated water quality sensors (measuring conductivity, temperature, and/or pH) detect
The system can detect the presence of gases such as hydrogen sulfide (H ₂ S), carbon monoxide (CO), oxygen (O ₂), and methane (CH ₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPELINE TRAJECTORY The embedded technologies produce a file containing X, Y, and Z coordinates. When combined with surface georeferencing information, this allows for precise mapping of the structure's position. Depending on the conditions, the system utilizes either four aerial turbines or two	INFILTRATION OF	anomalies in key parameters, indicating the presence of unwanted clean water infiltration.
monoxide (CO), oxygen (O ₂), and methane (CH ₄), along with their specific locations within the structure. An onboard LiDAR system digitizes the structure, allowing for the creation of cross-sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPELINE TRAJECTORY The embedded technologies produce a file containing X, Y, and Z coordinates. When combined with surface georeferencing information, this allows for precise mapping of the structure's position. Depending on the conditions, the system utilizes either four aerial turbines or two	CLEAN WATER (ECPP)	
Sectional views of the pipeline. Post-processing enables the generation of both transverse and longitudinal 2D sections, as well as 3D reconstructions in the form of point clouds. Through data fusion (combining point clouds, inertial data, and video), the post-processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. PIPELINE TRAJECTORY	GAS DETECTION	monoxide (CO), oxygen (O2), and methane (CH4), along with their specific locations within
processing workflows can generate 3D models of various structures, facilitating their integration into Geographic Information System (GIS) software. The embedded technologies produce a file containing X, Y, and Z coordinates. When combined with surface georeferencing information, this allows for precise mapping of the structure's position. Depending on the conditions, the system utilizes either four aerial turbines or two	DIGITIZATION	sectional views of the pipeline. Post-processing enables the generation of both transverse
TRAJECTORY combined with surface georeferencing information, this allows for precise mapping of the structure's position. Depending on the conditions, the system utilizes either four aerial turbines or two	3D MODELING	processing workflows can generate 3D models of various structures, facilitating their
PRODUCION		combined with surface georeferencing information, this allows for precise mapping of the
	PROPULSION	

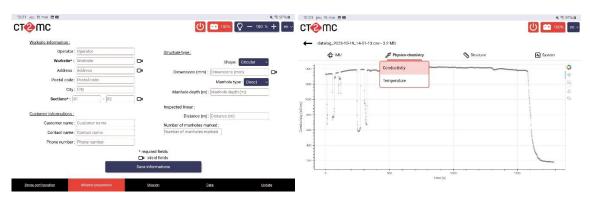






INSPECTION OF CONFINED STRUCTURES

It is possible to view the acquired data directly in the field thanks to our specifically developed software: a user interface accessible on-site via PC or tablet.



Our vehicles are complemented by a range of accessories specially developed to facilitate the deployment of our products, such as a system for lowering and retrieving the robot within the networks, in order to reduce human risk by limiting access to the networks.



Technical Specifications – The content of your product will be defined in your commercial offer:		
	1 HD camera – 360°, 5.2k (30fps), 3K (60fps)	
Video Acquisition	Optional: live video feed available.	
360° Lighting	4 lamps ranging from 100 to 1500 lumens, 3000 K, with adjustable	
360° Lighting	light intensity.	
	Single-beam or rotating sonar: generates a sediment profile over a	
Sediment Measurement	range of 50 mm to 6 m.	
Seament Weasurement	Frequency: 1 Hz at 1 m (then 0.5 s per additional meter), 400	
	measurement points, 2 mm resolution.	
Positioning and Digitalization	Via positioning beacon with UWB technology: 1D, or via multi-	
Positioning and Digitalization	sensor post-processing of the structure: 3D point cloud.	
Sound Information	Buzzer < 96 dB, intermittent signal.	
Visual information	LCD screen displaying timestamp and validation of proper drone	
Visual information	operation via the user interface (UI).	
Data recording	4 Hz, .csv file directly on the UI.	
Gaz sensors	Measurement of levels: H_2S , CH_4 , CO , O_2 (optional).	
Customization	Customizable shell and deck color.	
Packaging	Transport cases for the drone and beacons.	
Handling	Provision of the following peripheral equipment (sold separately):	
Handling	Launch and retrieval system, and telescopic pole.	
Chargers	Charger for drone and accessories. Optional: fast charger.	
Decumentation	User manual in French and English.	
Documentation	Standard Operating Procedures for data retrieval and processing.	
Software	Multilingual UI in FR, EN, DE, ES, IT, PL, PT, and UZ.	
Software	Post-processing software in FR, EN, and PL.	
Warranty	Refer to our General Terms and Conditions of Sale (GTCs).	

contact@ct2mc.com v25_00

+33(0) 4 79 33 65 95

www.ct2mc.com



